

ELECTRONIC

WHEEL

ALIGNMENT

0.10

-0.05



TOE-IN

10°-12° 13°-14° 15°-16°

CAMBER



CASTER



KING PIN



INTERNATIONAL MOTOR CORP. Q102 2-10 ANTI-STATIC ASSEMBLED IN MEXICO INTERNATIONAL MOTOR CORP.



HPA

OPTOELECTRONIC

4801

CAMBER

TOE-IN

CASTER

ZERO

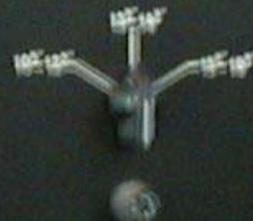
ELECTRONIC WHEEL ALIGNMENT

0.00

-0.08



TOE-IN



CAMBER



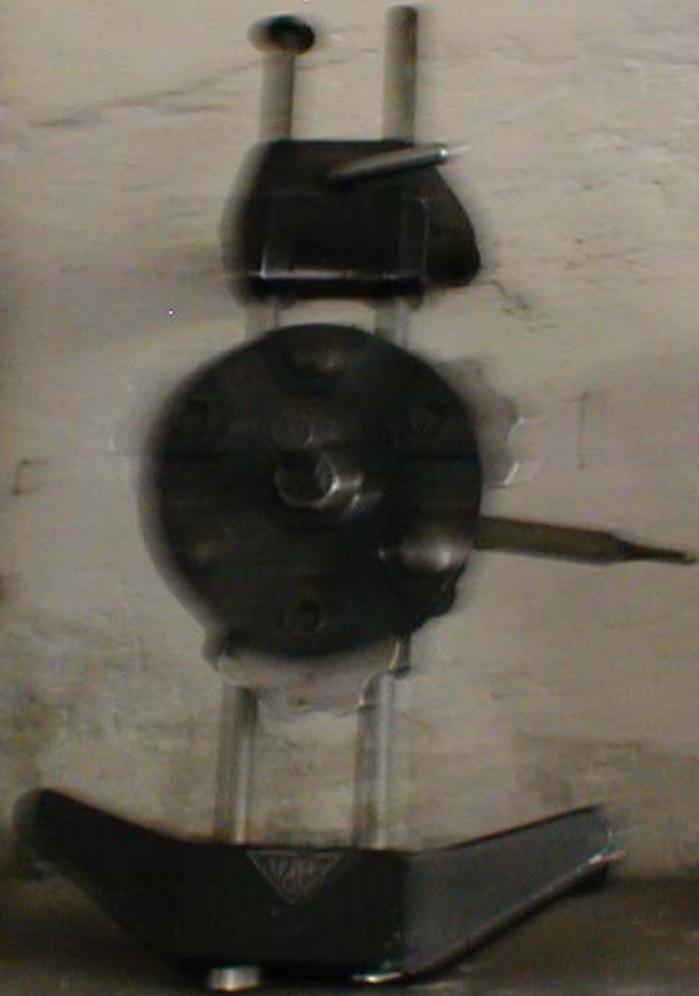
CASTER



KING PIN







PA

OPTOELECTRONIC

4801



PA

ELECTRONIC

4801



HC194D

CONTROLLO CONVERGENZA ANTERIORE

RUOTA ANTERIORE SINISTRA - 16mm

RUOTA ANTERIORE DESTRA - 1 mm

CONVERGENZA TOTALE - 2.6mm

CONVERGENZA PER fiat panda

DA 0 mm A -4 mm

controllo del 17 maggio 17 ore 15:27

HC090D

CONTROLLO CONVERGENZA ANTERIORE	
RUOTA ANTERIORE SINISTRA	- .8 mm
RUOTA ANTERIORE DESTRA	- .9 mm
CONVERGENZA TOTALE	- 1.7 mm

CONVERGENZA PER fiat panda
DA 0 mm A -4 mm

controllo del 17 maggio 17 ore 15:27

1937

HANNS-G